

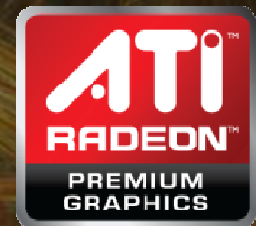
SIGGRAPH2008

Simulation and Rendering Massive Crowds of Intelligent and Detailed Creatures on GPU

Christopher Oat
Natalya Tatarchuk



AMD Graphics Products Group



Outline

- Motivation
- Crowd movement simulation on GPU
 - Global and local navigation and avoidance
- Lighting solution
- Crowd rendering and scene management on GPU
- Conclusions



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Driving Visual Experience Frontiers

- Our task is to push the envelope for interactive visual experience
 - “What does it mean to have better interactive experiences?”
- Beyond just the pretty face
 - We know we can do that... We’ve done it!
 - Can we make them think?



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We Can Even Make Them Dream!



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Motivation

- Making the gameplay more fun: A game is a series of choices...
 - It helps when choices are interesting!
- Artificial intelligence is ubiquitous in current games
 - Non-player and player characters require a form of AI
 - Path finding, obstacle avoidance, decisions, etc.



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Motivation

- CPU can spend $> 50\%$ time on path finding computations alone in games
 - Limits possible decision complexity
 - Thus we frequently see “zombie-like” NPCs
 - Gameplay suffers
- Emergent behaviors improve any game with many characters
 - Making it more fun!



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Top Level Overview

- Goal: Simulate and render massive crowds of characters on GPU at a scale that's both breathtaking and challenging
- Direct3D® 10.1
- Tessellation
- 4X MSAA
- HD resolution and HDR rendering



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A Smörgåsbord of Features

- Dynamic pathfinding AI computations on GPU
- Massive crowd rendering with LOD management
- Tessellation for high quality close-ups and stable performance
- HDR lighting and post-processing effects with gamma-correct rendering
- Terrain system
- Cascade shadows for large-range environments
- Advanced global illumination system



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Introducing the Froblins



Outline

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Motivation: Beware of Ghosts!!



Dynamic and Engaging World Through AI

- Combine global path finding with local avoidance and individual decisions
- Crowd movement is more stable and realistic solved on a global scale
 - Crowd dynamics similar to fluids
 - Agents “flow” towards the closest goal, along the path of least resistance
 - Froblins follow correct paths and do not “get stuck”



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Global Path Finding

- Based on *Continuum Crowds* [TCP06]
- Convert motion planning into an optimization problem
 - Use continuum model
 - Computational algorithms from optics
- Smooth flow-like crowd movement
 - Congestion avoidance and emergent behavior



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Pathfinding on GPU

- Numerically solve a 2nd order PDE on GPU with a computational iterative approach (eikonal solver)
 - Represent environment as a cost field
 - Through discretization of the eikonal equation
- Applicable to many general algorithms and areas

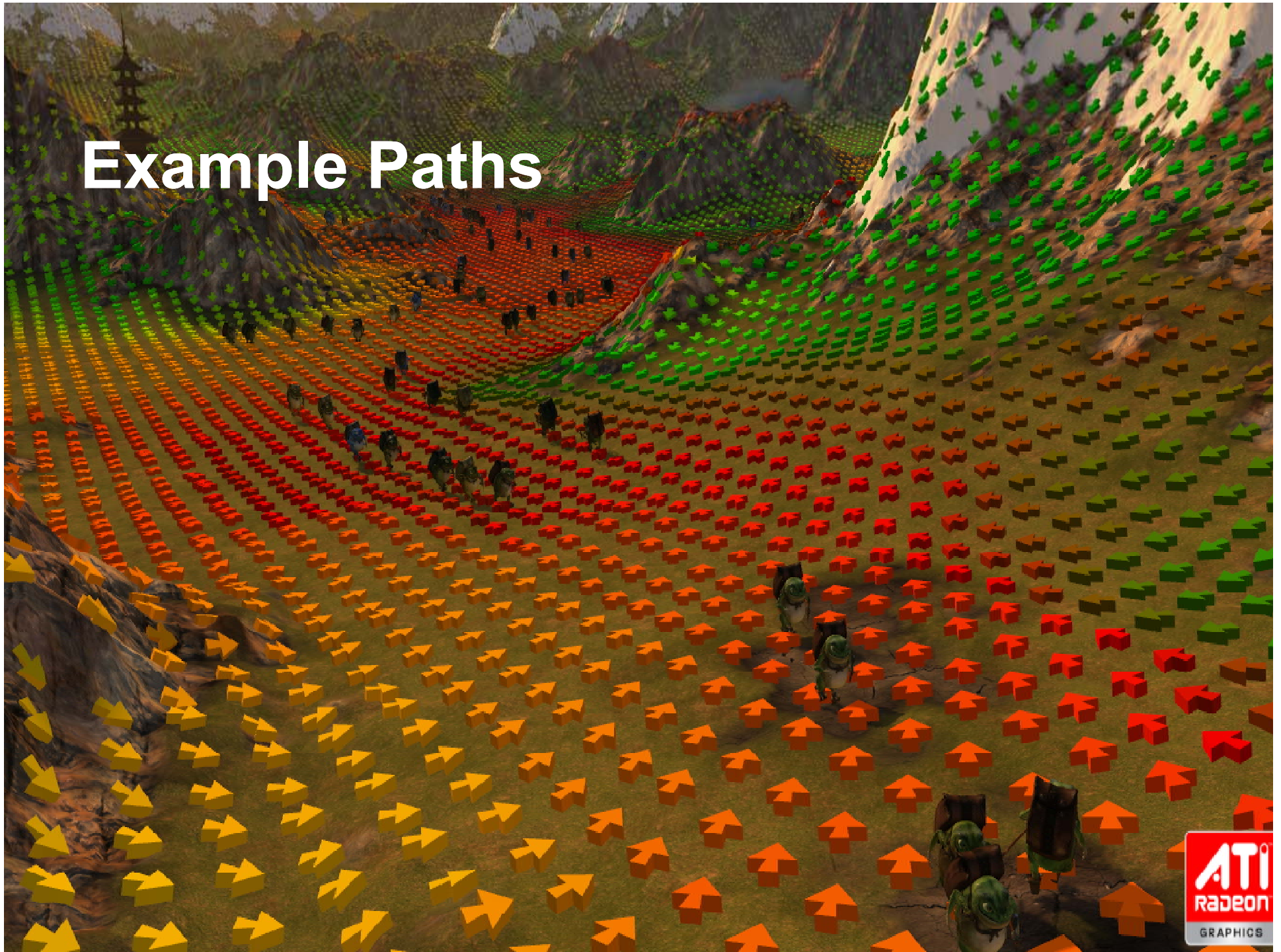


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Example Paths



Solver: From Cost to Travel Time

- Solve for travel time as a function of potential
- *Potential* φ = integrated cost F along shortest path to goal
 - Follow negative gradient
- Set potential = 0 at goal, eikonal equation elsewhere
- Comes from optimization algorithms

$$\|\nabla \varphi(x)\| = F$$



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Eikonal Solver via Fast Marching Method

- Emulates Dijkstra's shortest path algorithm
- A finite difference approximation to the continuous eikonal equation
 - Start from known potential ($\phi=0$ at goal) and propagate to neighbors until convergence
 - Compute potential for neighbor cells based on known cells
- Serial algorithm; requires an ordered data structure



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Parallel Eikonal Solver

- Using *Fast Iterative Method* [JW07]
- Use upwind finite difference approximation but no ordered data structures
- We use small grid resolutions (128^2 - 256^2)
- Solve for four goals at once
 - Taking advantage of vectorization – use RGBA FP16 texture
- Convergence determined empirically



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Environment As Cost Function

- Continuum Model models environment as a positive cost function
 - Can't be zero otherwise agents would move at infinite speed; add some small base amount
- Incorporate information about terrain and obstacles (static and dynamic)
 - Splat dynamic obstacles, including agents into the cost function

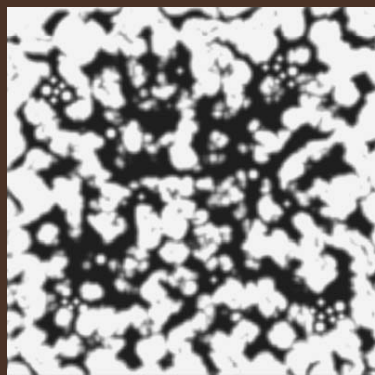


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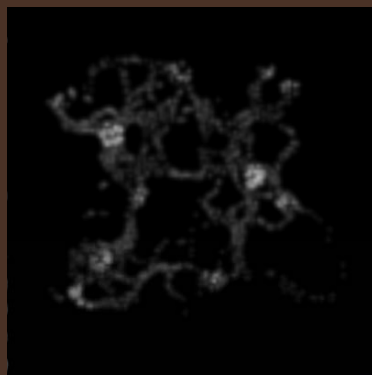


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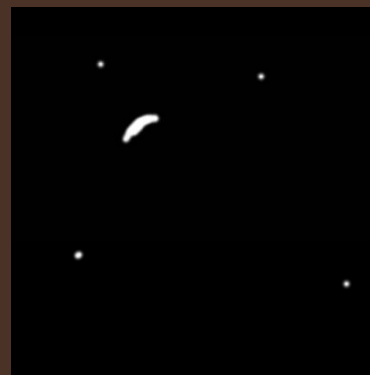
Cost Function Formulation



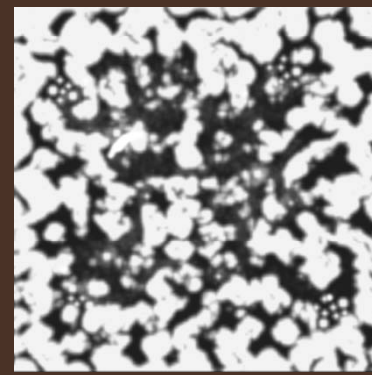
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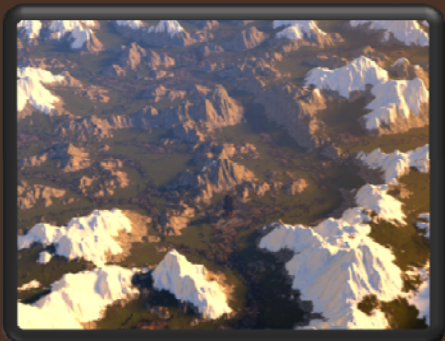


Static Cost

Agent Density

Hazards

Total Cost



Local Navigation and Avoidance

- Global model not great for local obstacles
 - Performance & No need to avoid agent far away
- Update velocity based on positions and velocities of nearby agents/obstacles
 - Based on Velocity Obstacle formulation [Fiorini and Shiller 1998]
 - See course notes for more details & **Jeremy Shopf's** talk on in ***Beyond Programmable Shading: In Action*** course



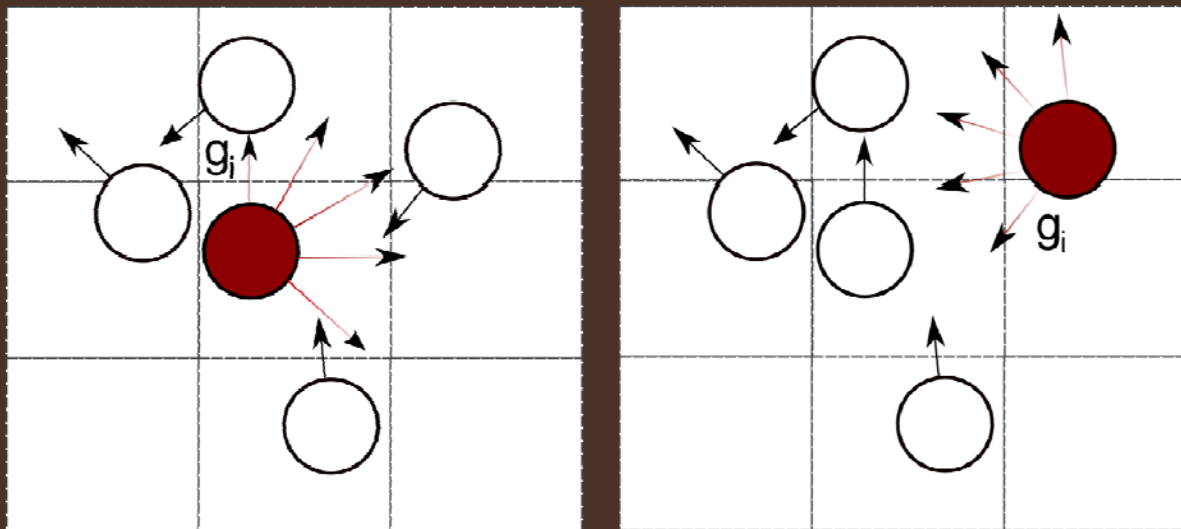
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Direction Determination

- Evaluate a fixed set of possible directions relative to global navigation direction



Spatial Queries

- Need to query nearby agent positions and velocities
- Spatial data structure
- Agents “binned” by position:
 - Bin Counter : Color buffer
 - Bin Array : Depth Buffer Array



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Spatial Data Structure: Bins

Agent Positions

	③		
①			⑤
			②
			⑥
			④

Bin Counter

0	1	0	0
1	0	0	1
0	0	0	1
0	0	0	2

Bin Array

	3		
1			5
			2
			4
			6

- World space position mapped to 2D index
- Bin Counter: color buffer, tracks bin loads
- ID Array: depth array, binned agent IDs



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Bin Queries

Agent Positions

			★

Bin Counter

0	1	0	0
1	0	0	1
0	0	0	1
0	0	0	2

Bin Array

	3		
1			5
			2
			4
			6



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Bin Queries

Agent Positions

			★

Bin Counter

0	1	0	0
1	0	0	1
0	0	0	1
0	0	0	2

Bin Array

	3		
1			5
			2
			4
			6

- Translate position to 2D index



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Bin Queries

Agent Positions

			★

Bin Counter

0	1	0	0
1	0	0	1
0	0	0	1
0	0	0	2

Bin Array

	3		
1			5
			2
			4
			6

- Translate position to 2D index
- Fetch load from *Bin Counter* (color buffer)

Bin Queries

Agent Positions

			★

Bin Counter

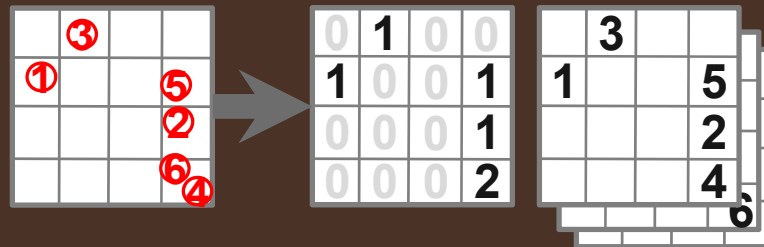
0	1	0	0
1	0	0	1
0	0	0	1
0	0	0	2

Bin Array

	3		
1			5
			2
			4
			6

- Translate position to 2D index
- Fetch load from *Bin Counter* (color buffer)
- Fetch agent IDs from *Bin Array* (depth array)
 - Efficient: *known number* of sorted agents

Data Structure Updates: Overview



- Binning is a multi-pass algorithm
 - Update one slice of *Bin Array* per pass
 - Once binned, agents removed from working set
 - Algorithm repeats until working set is empty
 - Overflow is possible & detectable

Data Structure Updates: Initialization

- Initialize data structure
 - Clear bin counter (color buffer) to 0
 - Clear bin array (depth array) to **MAX_DEPTH**
 - Working set is array of *all* agent IDs
 - No VB necessary



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Data Structure Updates: Pass 1

- Bind bin counter & first slice of bin array
- Draw working set as point primitives
- Vertex shader:
 - Map agent position to 2D bin array index
 - Set point's depth to normalized agent ID
- Pixel shader: output "1"
- Depth test: **LESS_THAN**



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Data Structure Updates: Pass 2...n

- Next slice of bin array bound as depth buffer
- VS: Sample ID from previous slice of bin array
 - Reject points less than or equal to previous
- GS: stream out non-rejected points
- PS: write pass number
- Depth test: **LESS_THAN**



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Results of Pass 2..n

- VS test ensures only points that haven't yet been binned get streamed-out and rasterized
- Depth test ensures the point with lowest ID gets binned
- Results in points binned in sorted order
 - Like depth peeling
- Stream-out buffer becomes new working set



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Early Termination

- We want to halt the algorithm once all points are binned
 - Do not query size of stream out buffer each pass
 - CPU/GPU synchronization results in pipeline stalls
- Would like to hand the whole thing off to the GPU to control execution



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Avoiding Synchronization Stalls

- We know max number of iterations
 - Number of bin array slices
- Make all the draw calls for the max number of iterations
 - Use cascading predicated draw calls
 - Use along with “DrawAuto” to issue draws
 - Predicate on number of stream-out elements



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Avoiding Synchronization Stalls

- GPU terminates algorithm once all agents are binned
 - Once working set (stream out buffer) goes to 0
 - Remaining draw calls are skipped
- The algorithm either terminates or overflows



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Binning on the GPU

- GPU Binning
 - Efficient queries
 - Early-out on empty bins, known bin load, sorted order
 - Overflow detection
 - Stream-out reduction of working set
 - GPU termination control
- Many applications beyond local avoidance

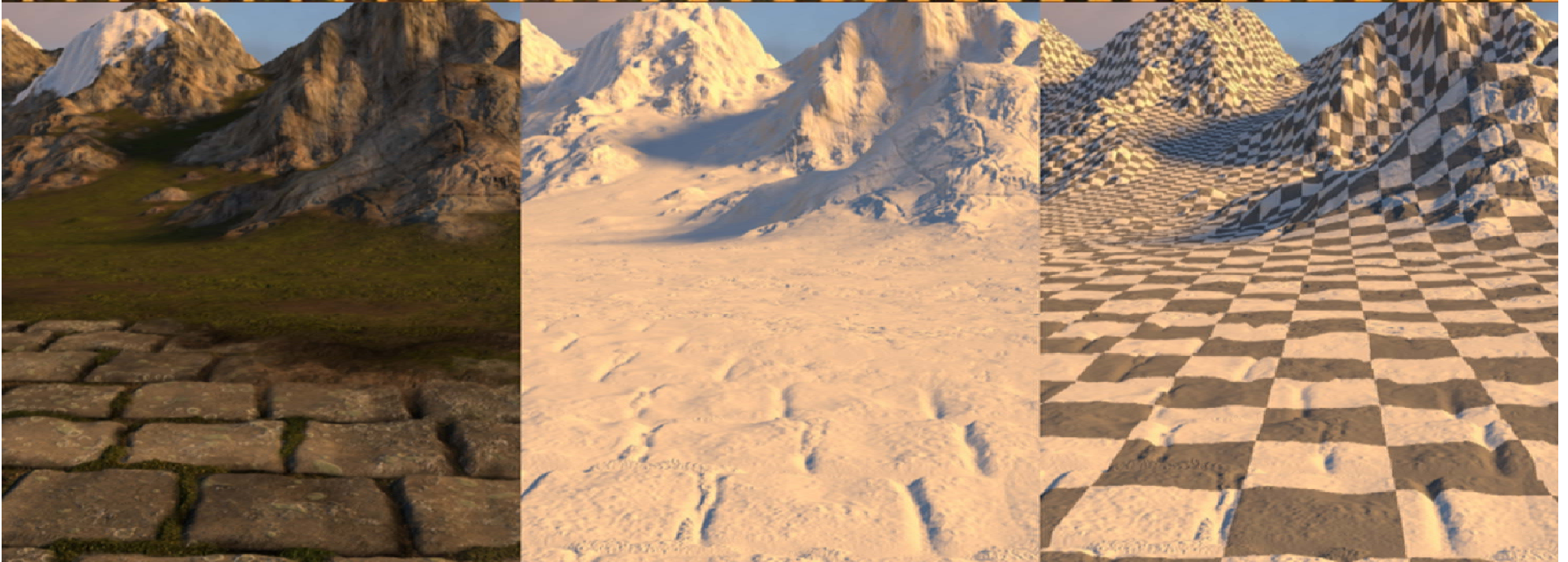


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Spherical Harmonic Light Map



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Diffuse lighting with Shadow Map

- Extracted dominant directional light: L_d
 - Dominant directional light color: L_c
- Left over residual lighting environment: L_e
- Dynamic shadow term: V_s
- Surface normal: N

$$\max(N \cdot L_d, 0) * L_c * V_s + \text{SH_Eval}(N, L_e)$$



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Dynamic Shadows Cast on Terrain



- Dynamic characters cast shadows on terrain
 - Shadow map shadows mingle with SHLM shadows
 - Shadow map attenuates *dominant* lighting term



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Double Shadows



- Results in double shadows...
 - Characters in shadow still cast shadows



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Detecting Direct Sun Light

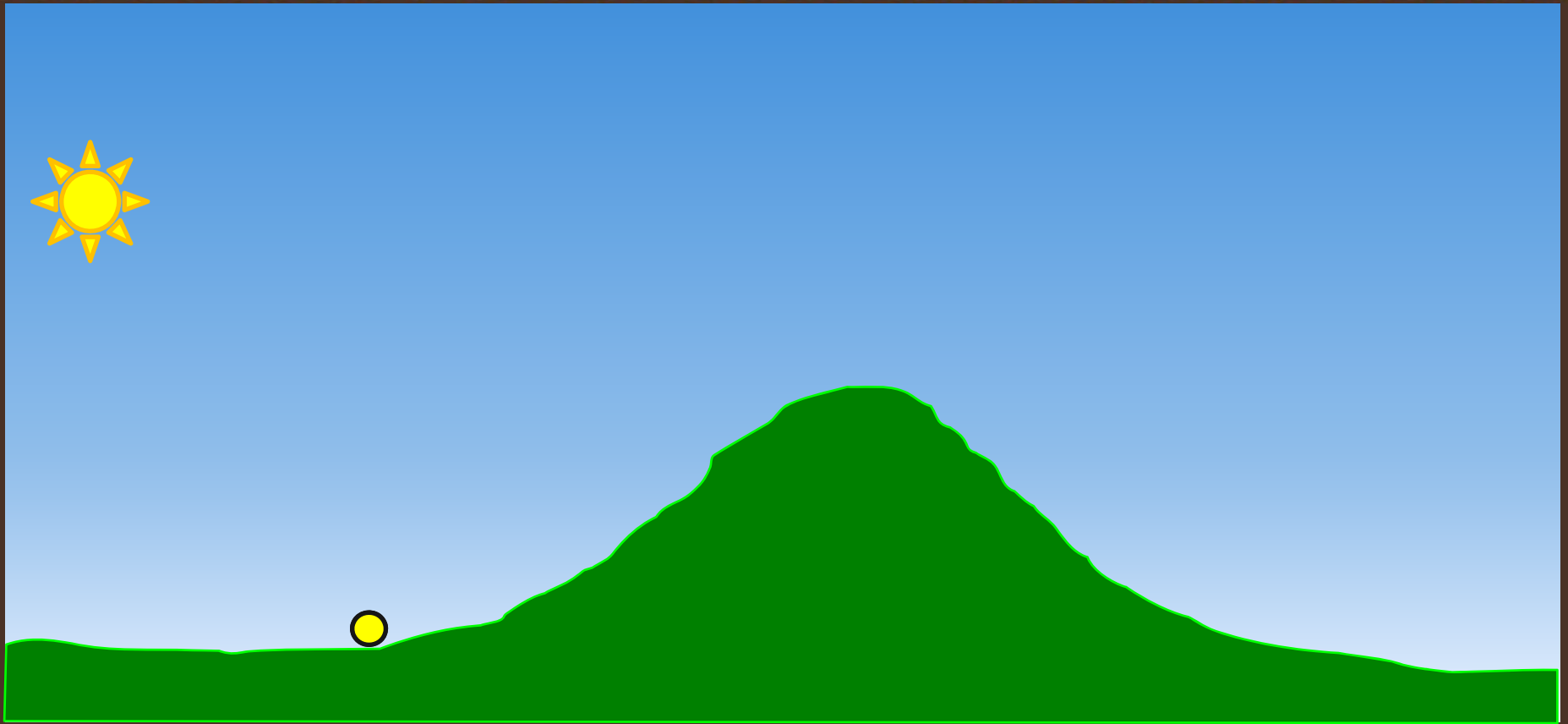


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Detecting Direct Sun Light

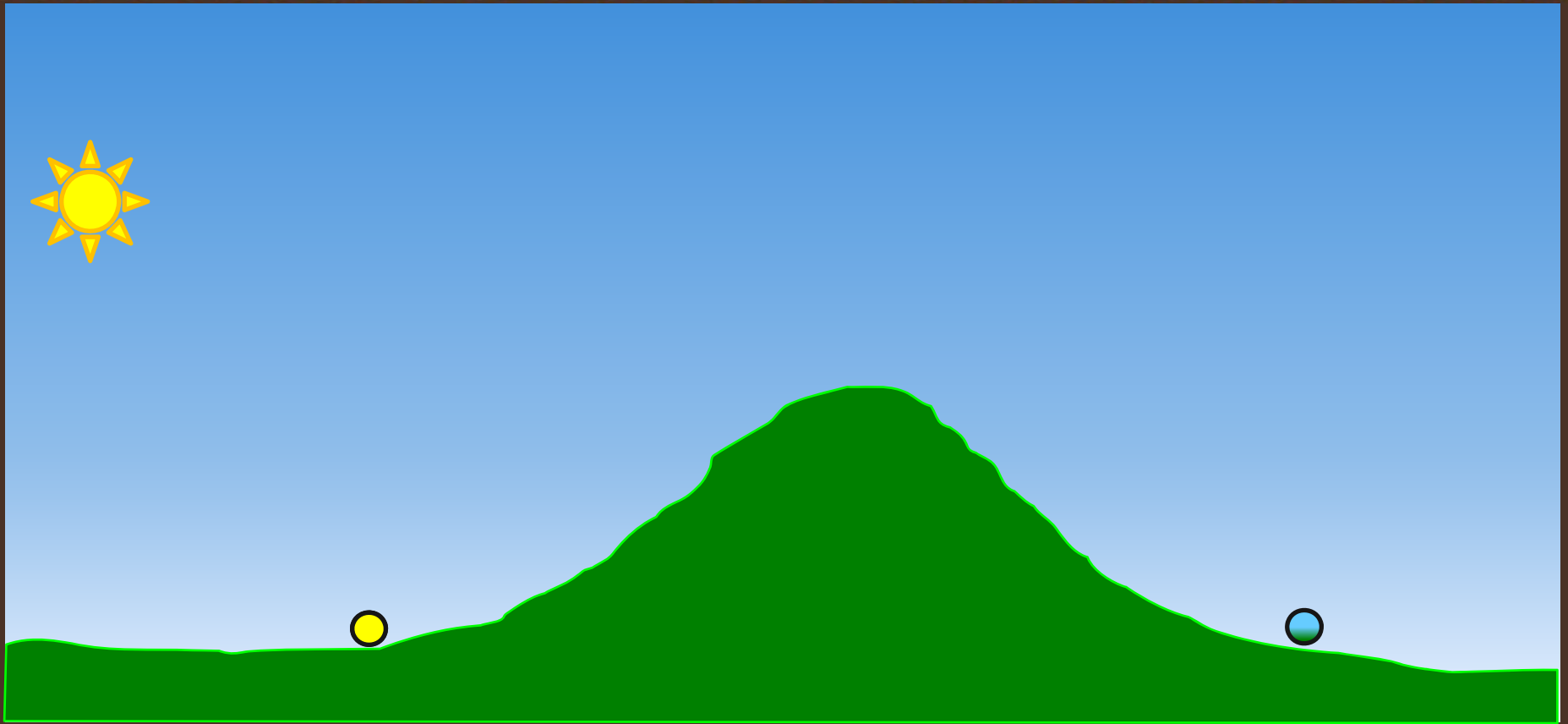


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Detecting Direct Sun Light

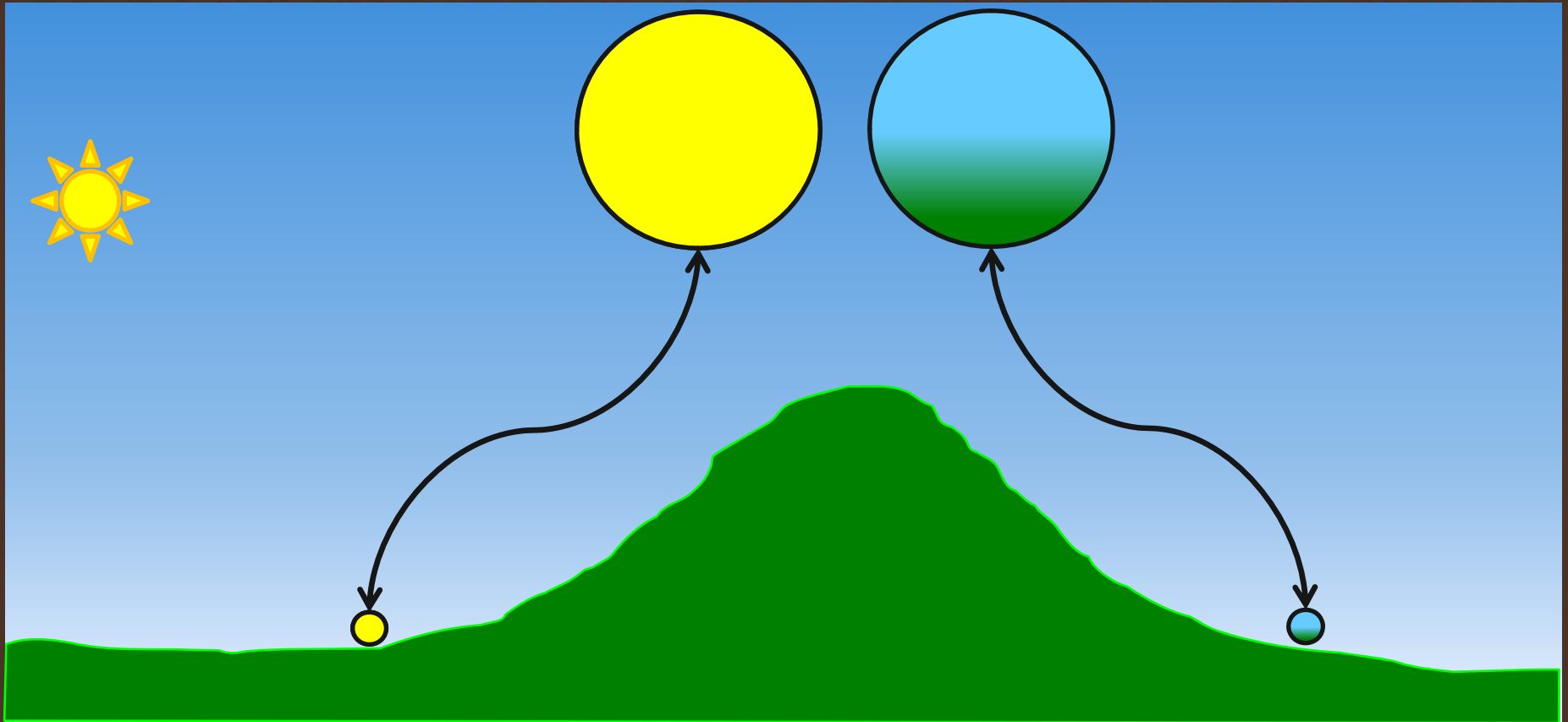


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Detecting Direct Sun Light



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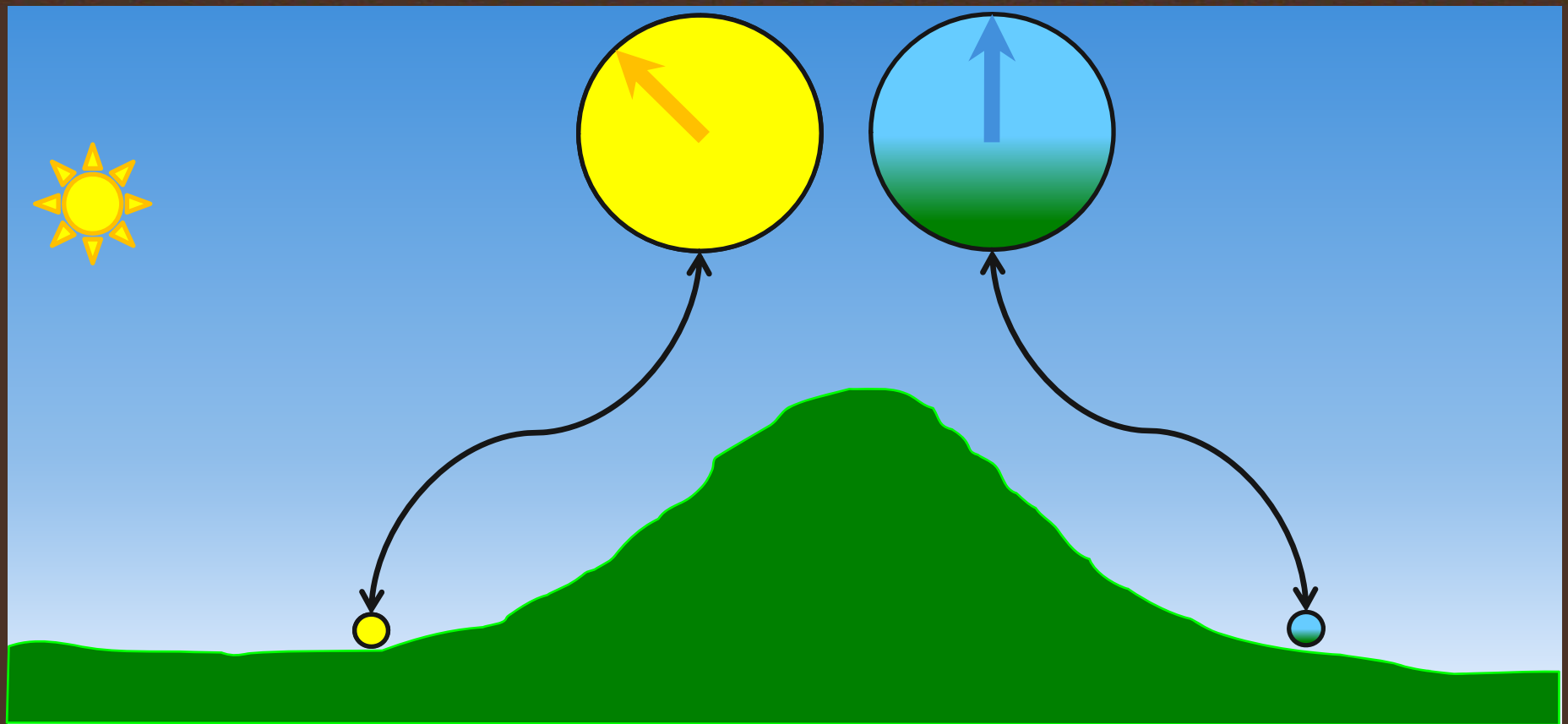
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Detecting Direct Sun Light



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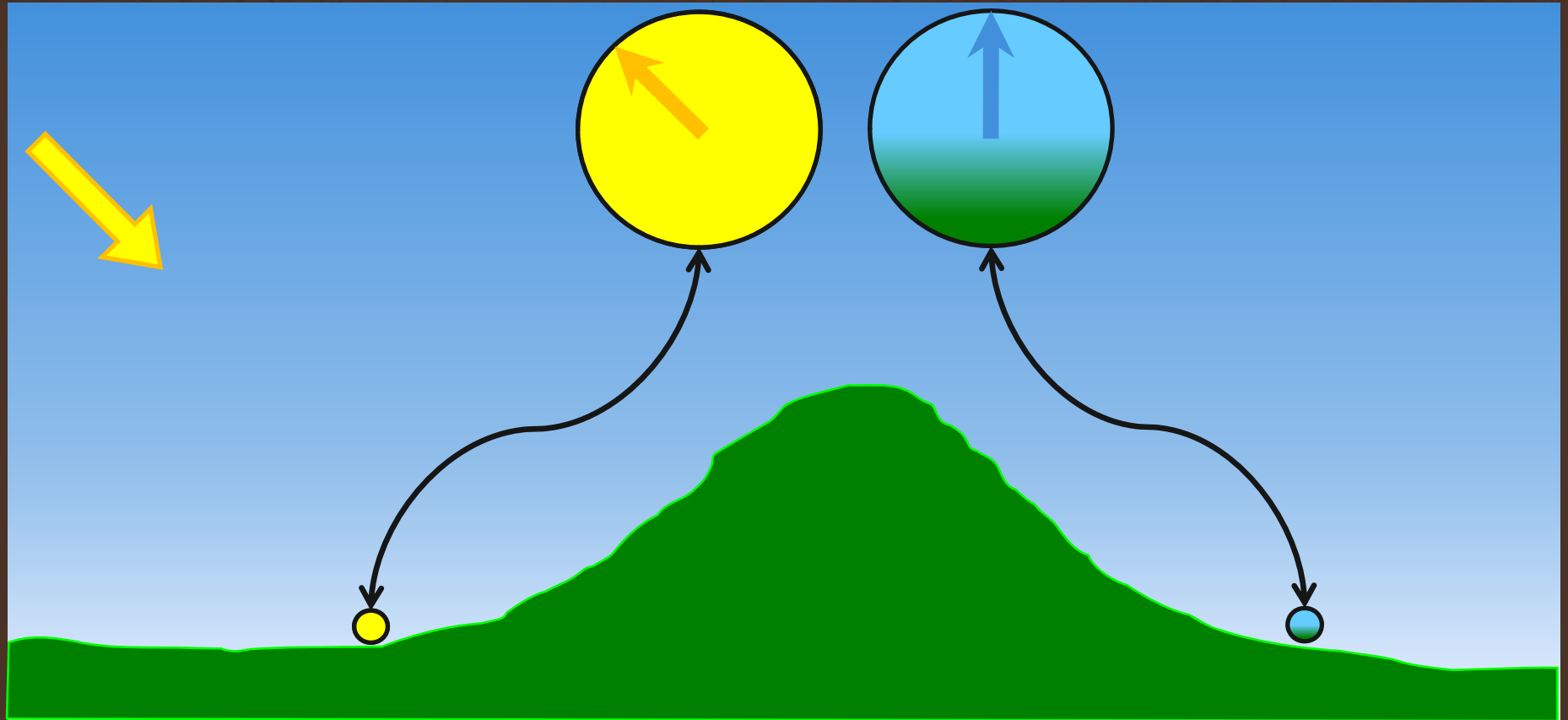
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Detecting Direct Sun Light

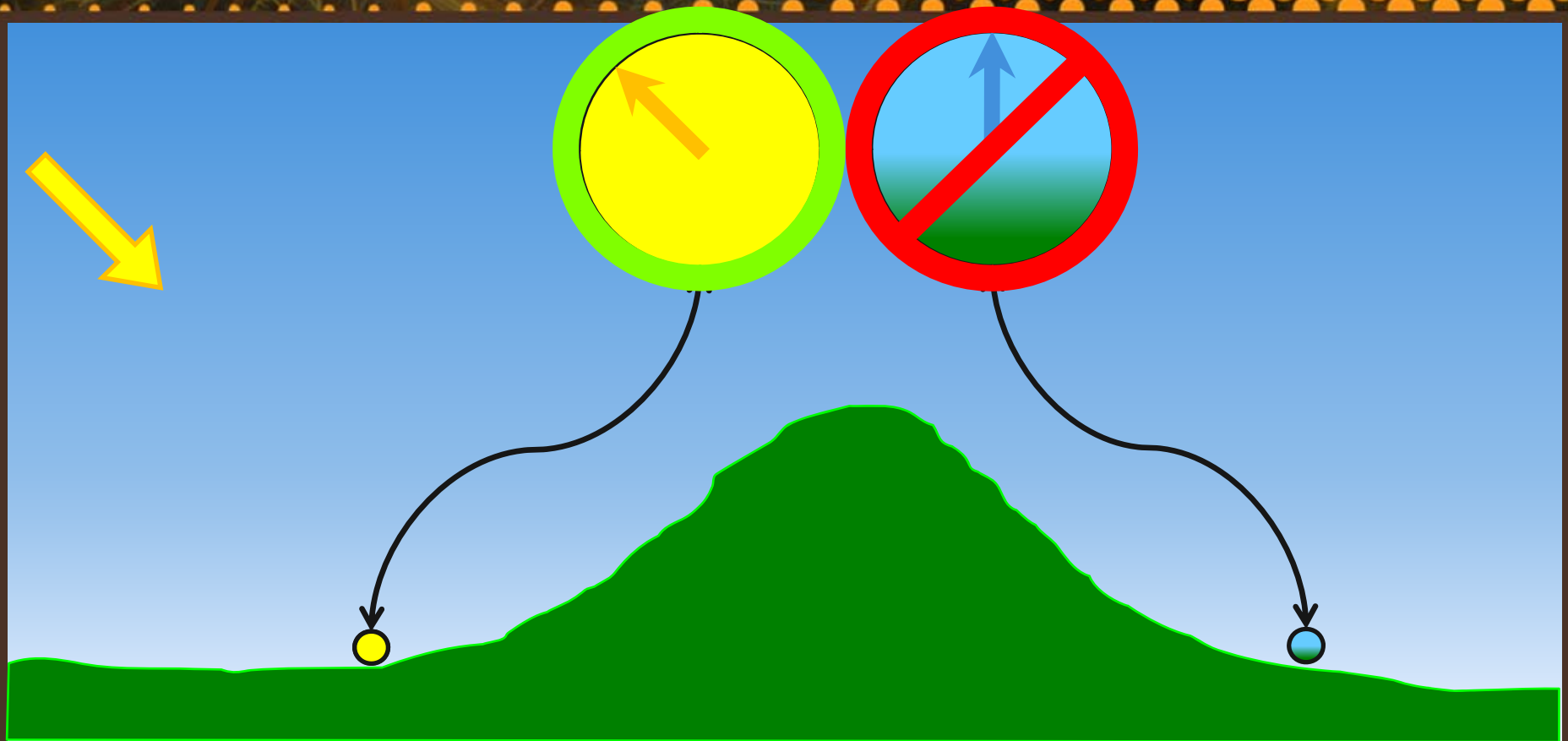


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Detecting Direct Sun Light



Double Shadow Fix



- Shadow map only used on non-occluded regions of terrain



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Outline

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The Need for GPU Character Management

- Need scalability and stable performance
- Don't want to render thousands million-poly characters
 - Wasteful if details are unseen
- CPU side character management is impractical when doing GPU simulation
 - Requires a read-back
- Solution: Perform GPU –side scene management



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GPU Scene Management



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GPU Scene Management

- We use Direct3D®10.1 features for GPU scene management and level of detail management
- Render froblins as an army of instanced characters
- 3 discrete LODs
- Use tessellation to get maximum amount of details with stable performance for close-ups



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Geometry Shaders as *Filters*

- Act on instances
- A set of point primitives (instance data) as input
- Re-emit only points that pass a specific test
 - Discard the rest
 - Use *DrawAuto* for multiple tests or combine into a single GS invocation for efficiency



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GPU Character Management Overview

1. Render the occluder geometry
2. Construct the Hi-Z map
3. Run all characters through the view frustum culling filter
4. Results are run through the occlusion culling
5. Run through a series of LOD selection filters
6. Render each LOD



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View Frustum Culling

- Using the filtering GS perform view frustum culling
 - Using standard methods
- VS checks for intersection between character bounding volume and the view frustum
 - Regular methods apply
- If the test passes, the character is visible: emit it
 - Otherwise it's culled



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Occlusion Culling

- Render all occluders prior to rendering characters
- Determine which characters are occluded by the environment or structures
 - Use resulting depth buffer
 - Cull against arbitrary, dynamic occluders
- Novel formulation: *Hi-Z map*



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Hi-Z Map

- A hierarchical depth image
 - Uses the Z buffer information
- A mip-mapped, *screen-resolution* image
 - Each texel at level $i = \max$ (all texels at level $i - 1$)
- Does not require a separate depth pass



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Occlusion Culling with Hi-Z Map

- Use constructed Hi-Z map
- Examine the depth information for pixels covered by the object's projected bounding sphere
 - Compare the max fetch depth to the projected depth of the point on the sphere closest to the camera
- Conservative culling
 - Does not result in false culling
- Details in the course notes



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Hi-Z Map Construction

- Finest level – use the main depth buffer
 - DepthStencil view (with MS DB in Direct3D® 10.1)
- Generate the mip chain levels with *reduction* passes
 - Mind the dimensions – screen-space images don't mip well!
 - Use integer operations to avoid incorrect indexing



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Reduction Pass for Hi-Z Levels

- Render into one mip level while sampling the previous level
 - Rendering into smaller mip *reducing* the larger one
- Fetch 2×2 neighborhood and compute *max* value
- Fetch additional texels on the odd-sized boundary



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GS Filtering for LOD Selection

- Use a discrete LOD scheme
 - Each LOD is selected by character's distance to camera
- Three successive filtering passes
 - Separate the characters into three disjoint sets
 - LOD parameters easily specified for each set



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GS Filtering for LOD Selection

- Compute LOD selection *post* culling
 - Only process visible characters
 - Culling results are only computed once and re-used
- Render closest LOD using tessellation and displacement
- Conventional rendering for middle LOD
- Simplified geometry and shaders for furthest LOD



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Organize Draw Calls Around Queries

- Need instance count for issuing the draw call for each LOD
- This requires a stream out stats query
 - Can cause significant stall when results are used in the same frame issuing the query
- Re-organize the draw-calls to fill the gap between issuing the query and using the results
 - We perform AI simulation steps



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CPU Animation Sampling

- Traditionally matrix palettes are computed on the CPU per character
 - Loaded into constant store
- Limitations on the number of characters handled in one draw-call with this approach
 - Large crowds of characters require numerous draw calls
- GPU character management makes this tricky



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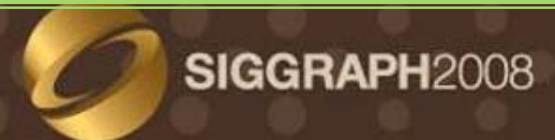
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Froblin Character Animation

- Agents have a set number of actions with associated animation sequence



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GPU Animation Sampling and Control

- At preprocessing time, bake animation data into texture arrays
 - Slice number = animation sequence
 - X and Y = key frame and bone index
- At rendering time, determine per-instance animation sequence index and time offset
 - During simulation in our case



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GPU Animation Sampling and Control

- Sample and interpolate animation data when rendering the character
 - Sample the animation textures



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Character Animation on GPU



- At preprocessing, flatten the transform hierarchy
- Compute bone transforms for each key frame transforming that bone into object space
- During simulation, assign an animation sequence to each character
 - Including a time offset into that sequence



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Animation Texture Layout



Bone 1

Matrix Row 0

Matrix Row 1

Matrix Row 2

Bone 2

Matrix Row 0

Matrix Row 1

Matrix Row 2



	Key 0	Key 1	...	→	...	Key N
Bone 1						
Bone 2						



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Character Animation on GPU



- During rendering VS fetches, interpolates, and blends the key frames for each bone
 - Using per-character information
- Each instanced character performs its skinning in object space
- Transforms the result using its position and orientation



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Tessellation and Crowd Rendering

- Combine with Direct3D® 10 instancing support
- Render using interpolative planar tessellation
 - Fast evaluation
 - With displacement mapping for fine-scale detail
- Control tessellation level per-draw call
 - Use character location
- The same art assets as conventional rendering



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The Benefits of Tessellation

- Tessellation reduces memory footprint and bandwidth
 - Only store low resolution mesh
 - Always relevant, especially for consoles

	Polygons	Total Memory
Low resolution Froblin model	5160 polygons	VB/IB: 100K 2K x 2K 16 bit displacement map: 10MB
ZBrush High res Froblin model	>15M polygons	~270MB VB and 180MB IB storage



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The Benefits of Tessellation

- Scalability
- Stable and predictable performance

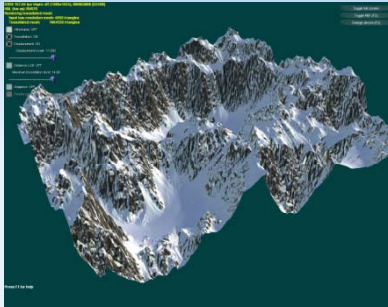
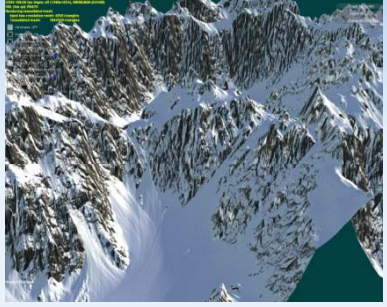


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Tessellation Performance Analysis

Rendering Mode	Num faces:	Far away view		Close-up view	
					
$N_T = 411 \times N_L$		ATI Radeon™ HD 4870	ATI Radeon™ HD 2900 XT	ATI Radeon™ HD 4870	ATI Radeon™ HD 2900 XT
Original low res mesh (N_L)	4,050 triangles	852 fps	359 fps	850 fps	275
Continuously tessellated mesh (N_T)	1.6 M triangles	232 fps	143 fps	213 fps	101
Adaptively tessellated mesh N_A	Dynamic, $1.6M > N_A > 4K$ triangles	845 fps	356 fps	574 fps	207



*Configuration: AMD reference platform with AMD Athlon™ 64 X2 Dual-Core Processor 4600+, 2.40GHz, 2GB RAM.
Motherboard: ASUSTek M2R32-MVP. Memory: DDR2-800 400 MHz.
Operating System: Windows Vista® SP1.

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Tessellation Pre Direct3D® 11

- GPU tessellation already available
 - Supported on Xbox™ 360
 - ATI Radeon™ HD 2000 Series and beyond: supported on all models
 - *Even on the integrated chipsets!*
- Subset of Direct3D® 11 tessellation features
- Contact AMD ATI developer relations for details on accessing tessellation



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Preview and Prepare for Direct3D® 11

- Support across most APIs gives you best bang for the buck for this feature
 - Support on Microsoft® Windows® XP as well as Microsoft® Windows® Vista
 - PC versions can use Xbox™ 360 native features
 - Reach more players
- Developing artwork takes time
 - Integrating tessellation early gives you and your artists time to design and polish

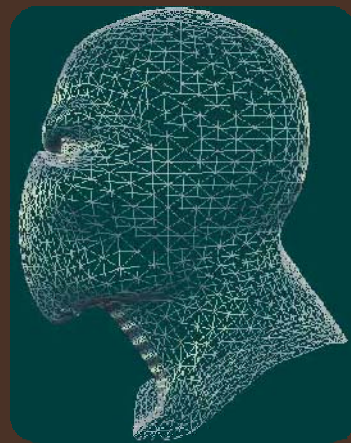


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Tessellation Process



**Super-prim
Mesh**

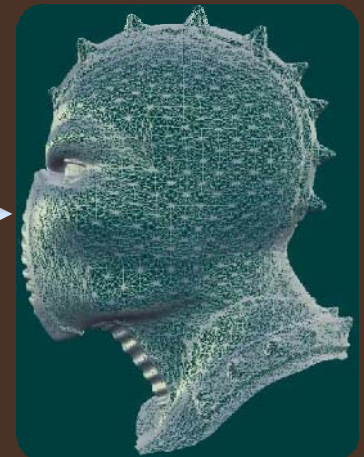
Tessellator



**Tessellated
Mesh**

**Evaluate
surface
positions**

**Add
displacement**



**Tessellated and
Displaced Mesh**



**Displacement
Map**



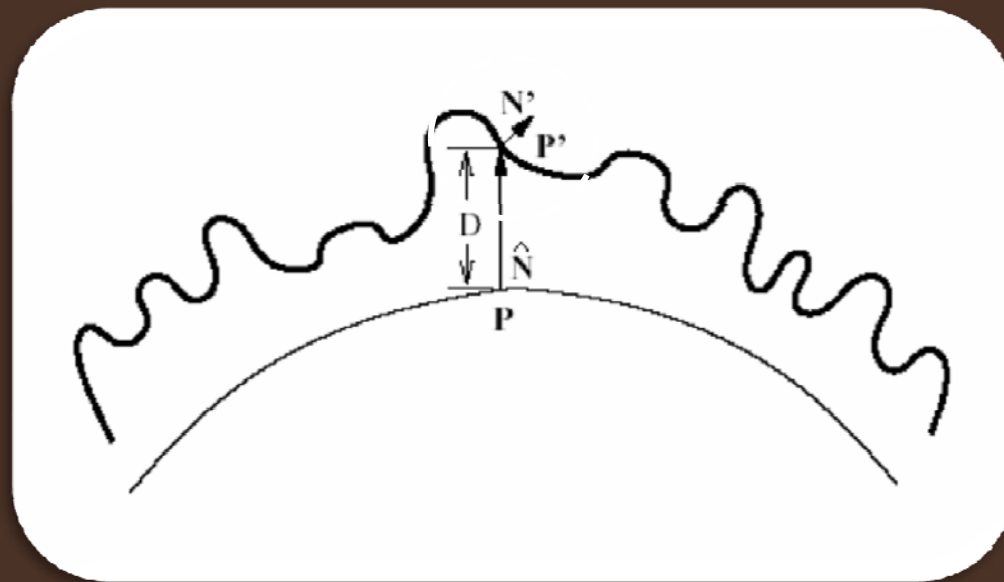
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Combining Normal Maps and Displacement Maps

- As we displace, we change the actual displayed normal



Lighting with Displacement

- Use TS normal maps even with displacement
- Generate displacement and normal maps using the same tangent space
 - The same TS computations for preprocessing
 - The normal encoded in TS normal map will match the normal from displacement



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Regularly drawn Froblin

No tessellation used



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**High Detail Froblin with
Tessellation and
Displacement Mapping**



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Froblin Close-up:

No tessellation



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**Froblin With Tessellation
and Displacement Mapping
Close-up**



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Tessellated Characters LOD Control

- Dynamic number of detailed characters in view
 - Simulation changes interactively, no a priori control
- Need stable frame rate in dense crowd simulations
- Compute tessellation level as a function of tessellated characters in view
 - Avoid polygonal count explosion



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Tessellation Level Computation

$$T_l = \text{clamp}(M T_{\max} / N, 1, T_{\max})$$

- N characters rendered with tessellation
- Bound the number of amplified triangles
- Primitive count never exceeds than the cost of M fully tessellated characters



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Control Cage Pre-Pass

- Perform animation and transformation on control cage in a *pre-pass*
 - Allows for more complex per-vertex operations
- Combine with vertex (de)compression for reducing bandwidth

Pass 1: Control cage animation and transforms



Stream Out Buffer



Pass 2:
Tessellate the control cage



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PrePass and Vertex Compression

- Shader-based vertex compression / decompression
- Reduce stream out memory footprint between the pre-pass and tessellated pass
- Reduce fetch bandwidth for tessellated pass



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PrePass and Vertex Compression

- Pack transformed vertex positions into 128 bit format
 - Lets us load each vertex with one fetch
 - Gives as much as 30% speedup
 - More details in the course notes



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Froblin Land: Terrain Rendering



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Froblin Land: Terrain Rendering

- Smooth, crack-free LOD without degenerates
- Tessellation and instancing
- Leverages Direct3D® 10.1 functionality to help minimize memory footprint
- Complex material system



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Froblins Performance Details*

- Staggering polygon count at interactive rates (>20fps)
 - From 900 polygons -> 6K -> 1.6M at the closest tessellated level of details
 - Up to 18M triangles per frame at fast interactive rates
 - 6M-8M triangles on average at 20-25 fps
- Full high quality lighting and shadowing solution
 - Rendering all objects into multiple shadow maps more than doubles polygon count per frame
- Rendering and simulating high quality detailed 3K froblins at 21 fps on average



*Configuration: AMD reference platform with AMD Athlon™ 64 X2 Dual-Core Processor 4600+, 2.40GHz, 2GB RAM.
GPU: ATI Radeon™ HD 4870 Graphics. Motherboard: ASUSTek M2R32-MVP. Memory: DDR2-800 400 MHz.
Operating System: Windows Vista® SP1.

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Simulation Performance Details*

- All modes render with 4X MSAA HDR and post-processing
- Simulate behavior and render > 65K agents at 30 fps
- AI simulation for 65K agents alone – 45 fps
- Rendering and simulating 65K agents – 31 fps
- Rendering 9,800,000 polygons each frame
- AI simulation executes with high efficiency resulting in ~1 *teraflops*!



*Configuration: AMD reference platform with AMD Athlon™ 64 X2 Dual-Core Processor 4600+, 2.40GHz, 2GB RAM.
GPU: ATI Radeon™ HD 4870 Graphics. Motherboard: ASUSTek M2R32-MVP. Memory: DDR2-800 400 MHz.
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Conclusions

- Practical and efficient simulation and rendering of large crowds of characters on GPU
- New GPU algorithms for
 - Global and local navigation and spatial data structures
 - Scene management
 - etc
- And a number of other advanced techniques!



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Learn More about Our Approaches

- All shaders are included in the course notes
- Course notes are available for download:
 - ACM Digital Library: <http://portal.acm.org/dl.cfm>
 - AMD Graphics Technical Publications webpage: <http://ati.amd.com/developer/techreports.html>



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Questions?



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